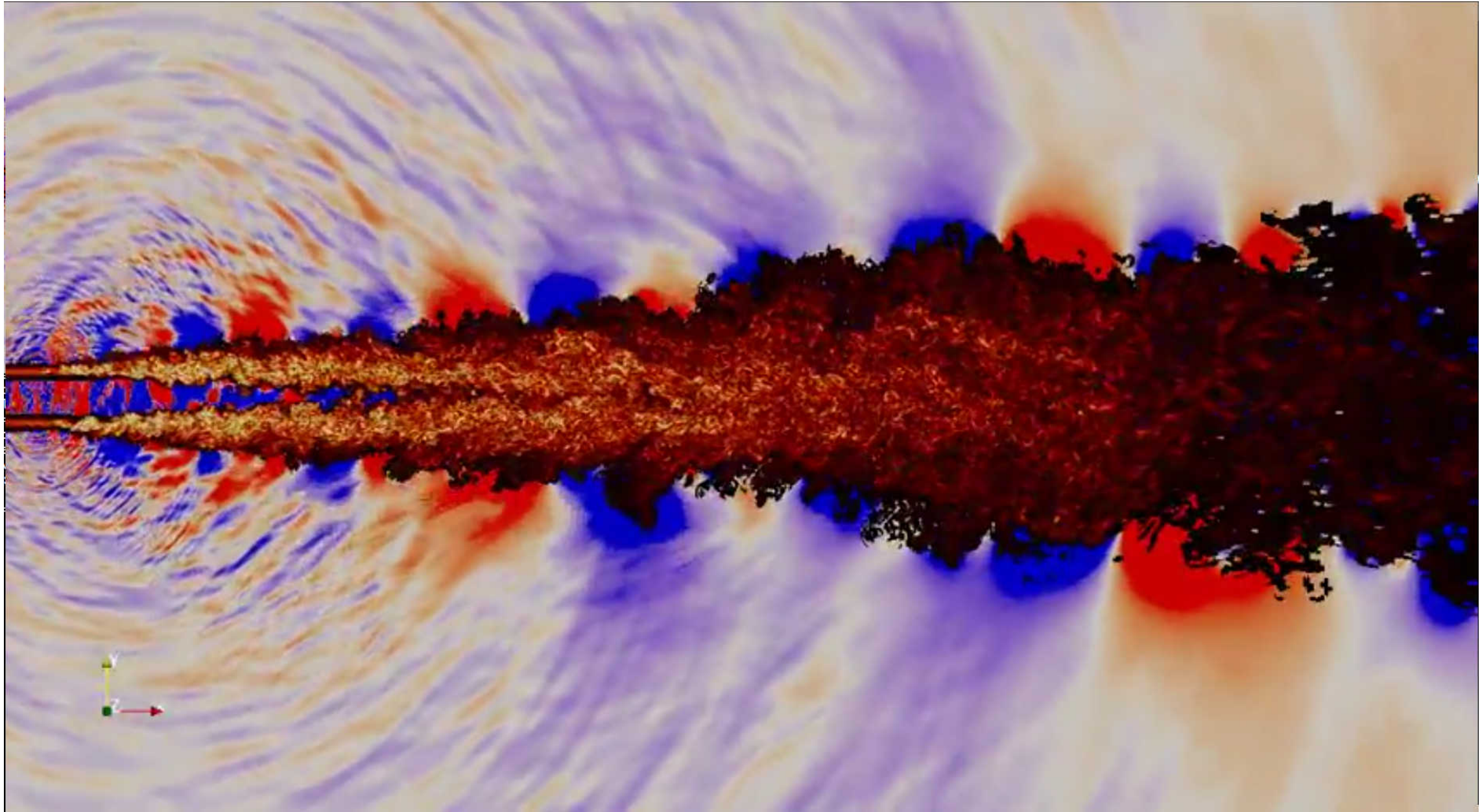


SBP Finite Differences

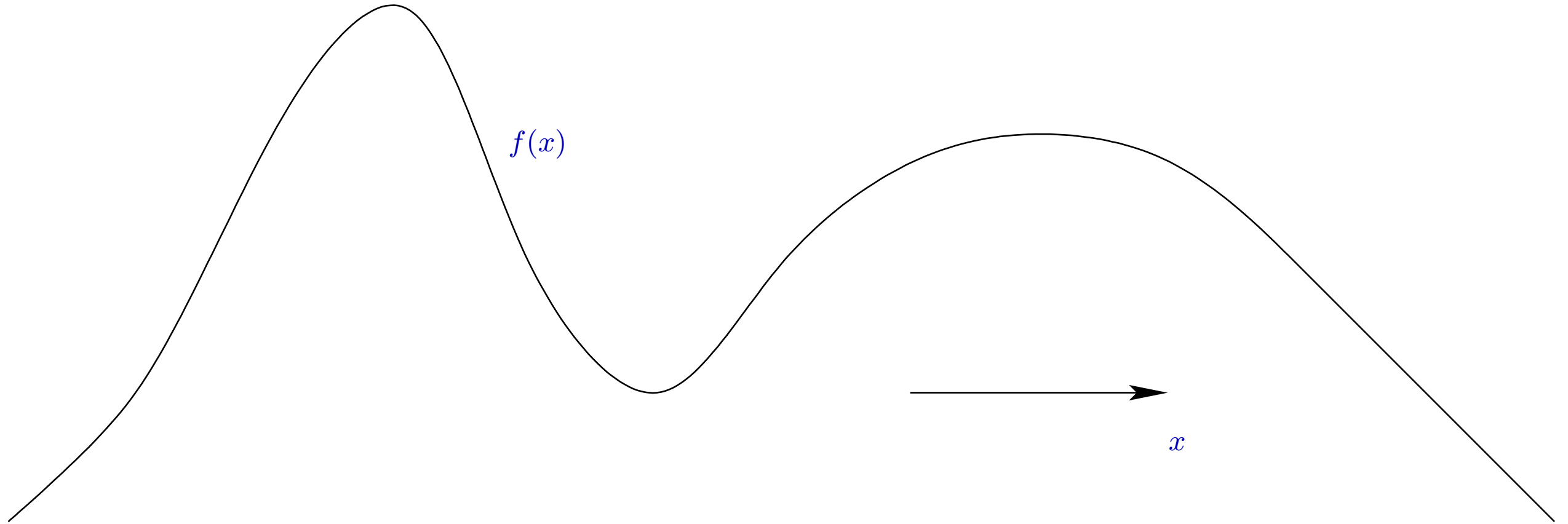
Dr Ed Brambley
Mathematics Institute & WMG
University of Warwick



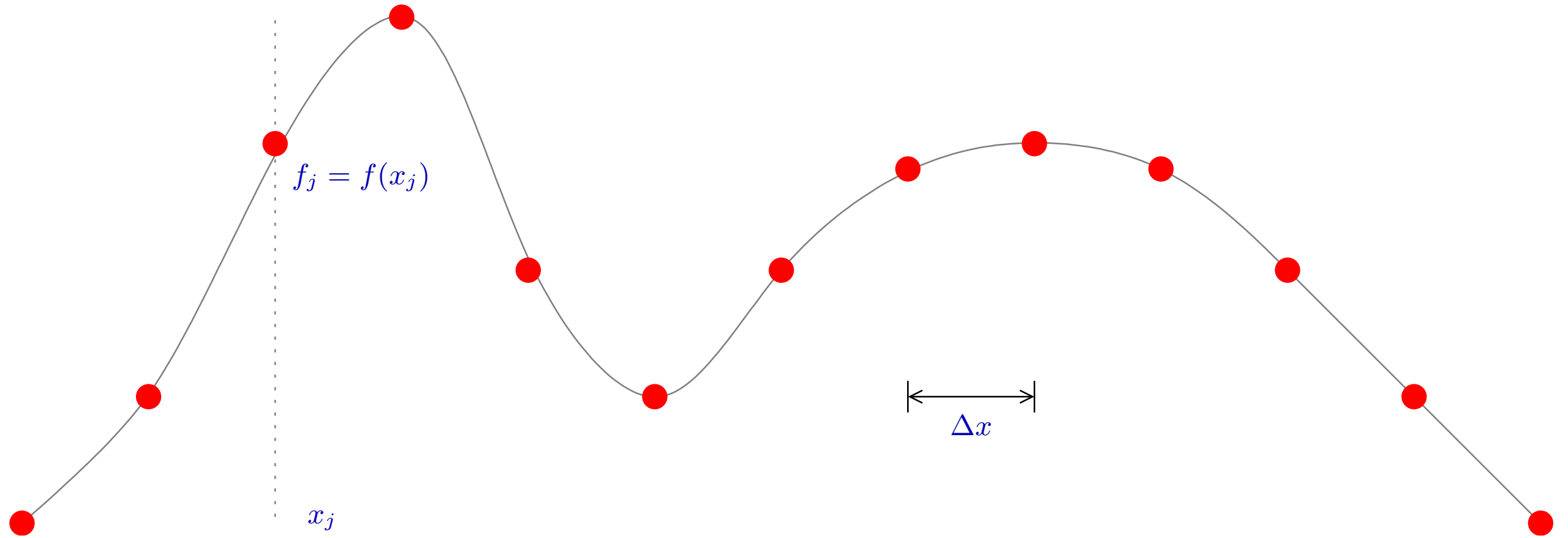
Sound from a jet



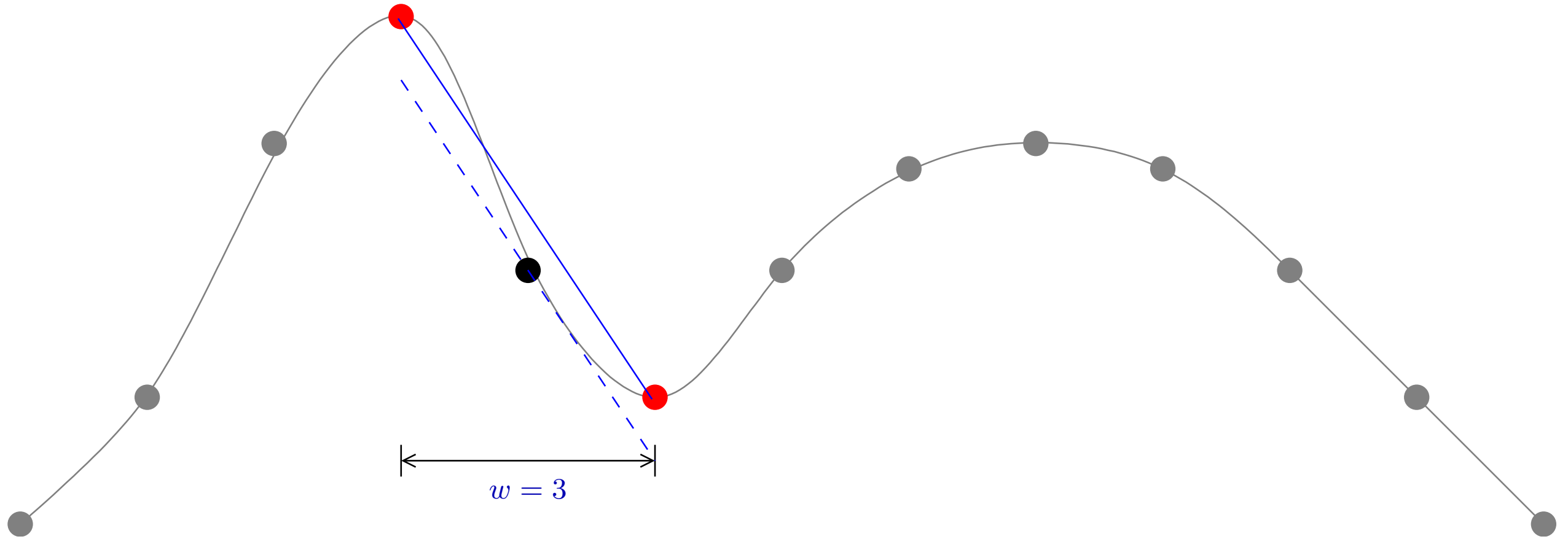
Finite Differences



Finite Differences



Finite Differences



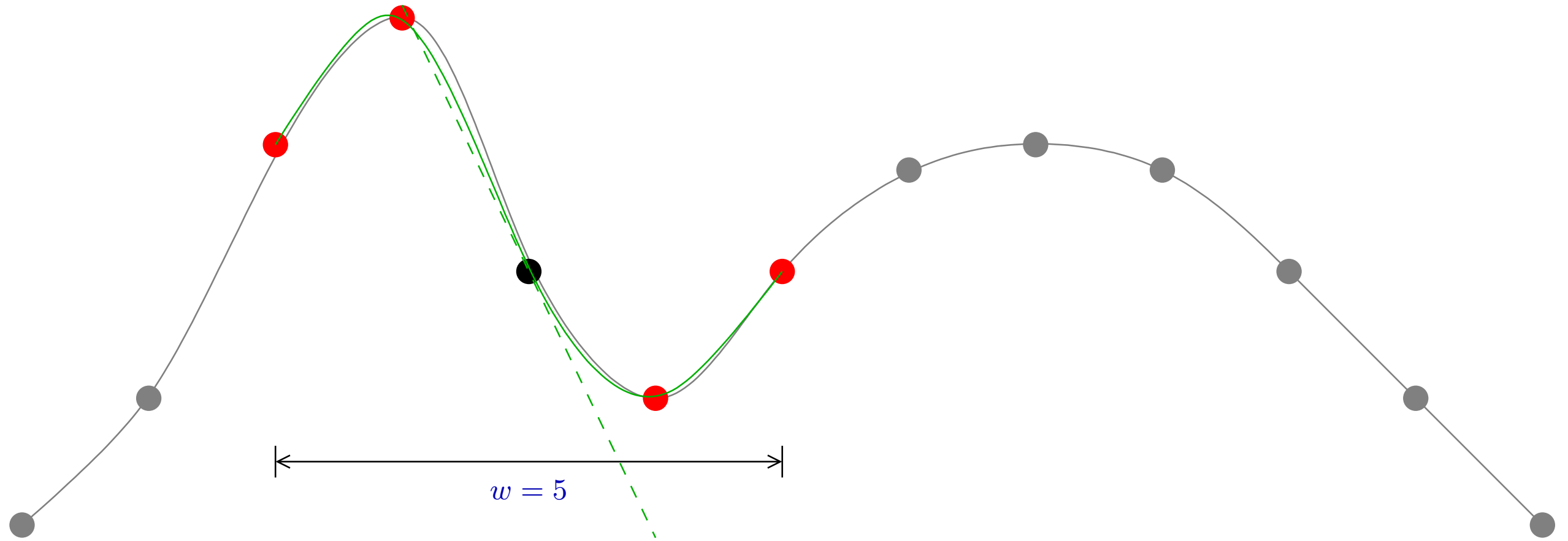
Could try:

$$f'_j = \frac{1}{\Delta x} (f_{j+1} - f_j) = f'(x_j) + O(\Delta x).$$

Better:

$$f'_j = \frac{1}{\Delta x} \left(-\frac{1}{2} f_{j-1} + \frac{1}{2} f_{j+1} \right) = f'(x_j) + O(\Delta x^2).$$

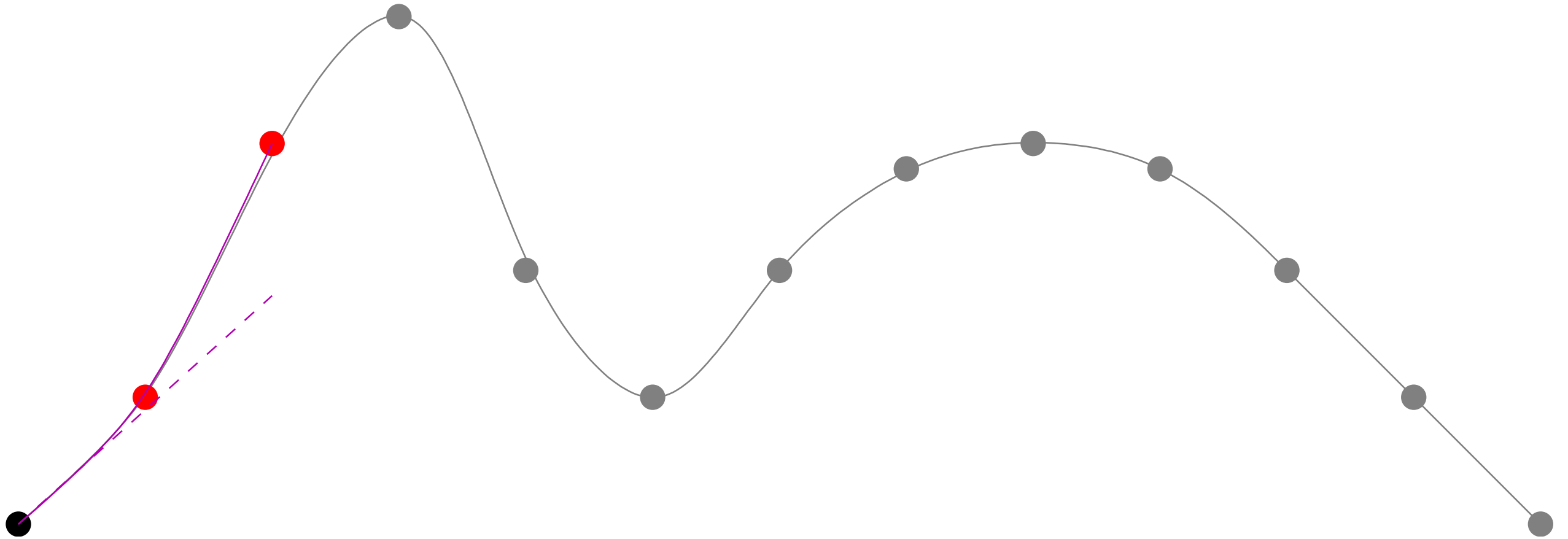
Finite Differences



Even better:

$$f'_j = \frac{1}{\Delta x} \left(\frac{1}{12} f_{j-2} - \frac{2}{3} f_{j-1} + \frac{2}{3} f_{j+1} - \frac{1}{12} f_{j+2} \right) = f'(x_j) + O(\Delta x^4).$$

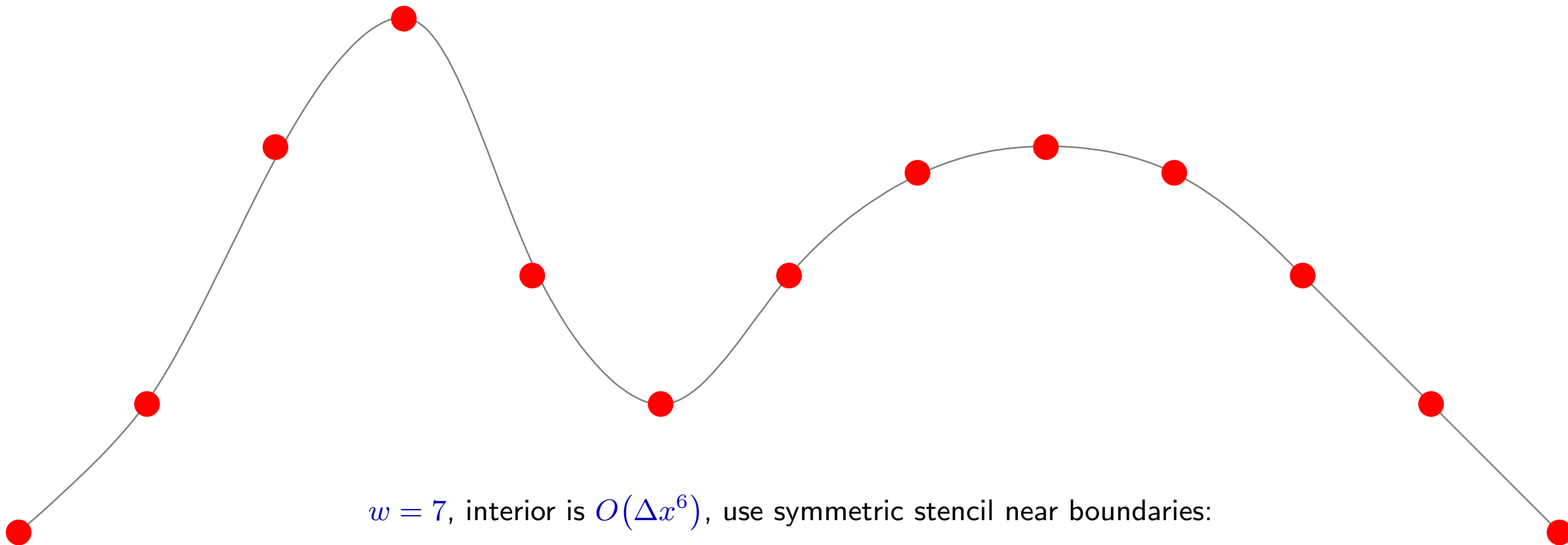
Finite Differences



At a boundary:

$$f'_j = \frac{1}{\Delta x} \left(-\frac{3}{2}f_j + 2f_{j+1} - \frac{1}{2}f_{j+2} \right) = f'(x_j) + O(\Delta x^2).$$

Finite Differences



$w = 7$, interior is $O(\Delta x^6)$, use symmetric stencil near boundaries:

$$\begin{pmatrix} f'_0 \\ f'_1 \\ f'_2 \\ f'_3 \\ f'_4 \\ \vdots \end{pmatrix} = \frac{1}{\Delta x} \begin{pmatrix} -3/2 & 2 & -1/2 & & & & & & \\ -1/2 & 0 & 1/2 & & & & & & \\ 1/12 & -2/3 & 0 & 2/3 & -1/12 & & & & \\ -1/60 & 3/20 & -3/4 & 0 & 3/4 & -3/20 & 1/60 & & \\ -1/60 & 3/20 & -3/4 & 0 & 3/4 & -3/20 & 1/60 & & \\ \vdots & & \ddots & \ddots & \ddots & \ddots & \ddots & & \\ & & & & & & & & \ddots \end{pmatrix} \begin{pmatrix} f_0 \\ f_1 \\ f_2 \\ f_3 \\ f_4 \\ \vdots \end{pmatrix}$$

Test case

- System to solve:

$$\frac{\partial p}{\partial t} + \frac{\partial v}{\partial x} = -\mu(x)p,$$

$$\frac{\partial v}{\partial t} + \frac{\partial p}{\partial x} = -\nu(x)v,$$

Boundary conditions: $v(0, t) = v(L, t) = 0$

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Boundary conditions: $v(0, t) = v(L, t) = 0$

- There is an analytic solution (using characteristics). If $\mu \equiv \nu$, at time $t = 2L$,

$$p(x, 2L) = Ap(x, 0) \qquad v(x, 2L) = Av(x, 0) \qquad \text{where } A = \exp \left\{ -2 \int_0^L \mu(x) dx \right\}$$

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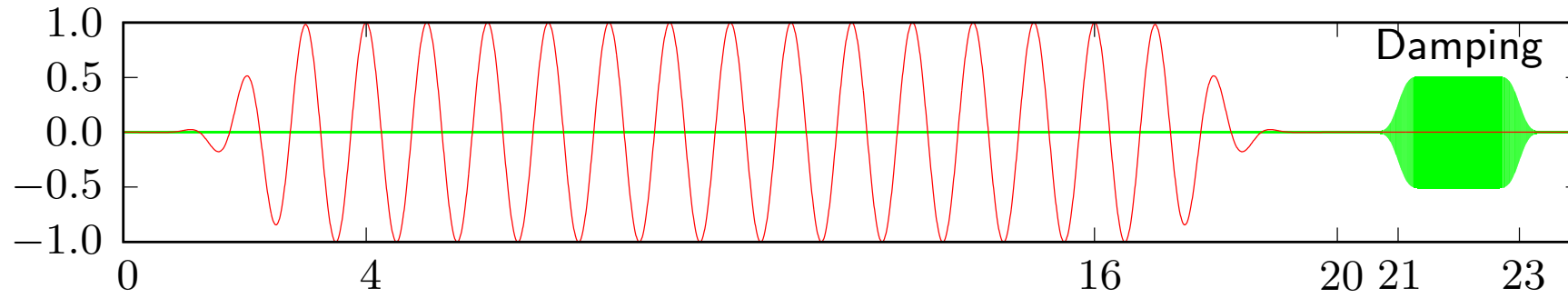
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- Conserved laws:

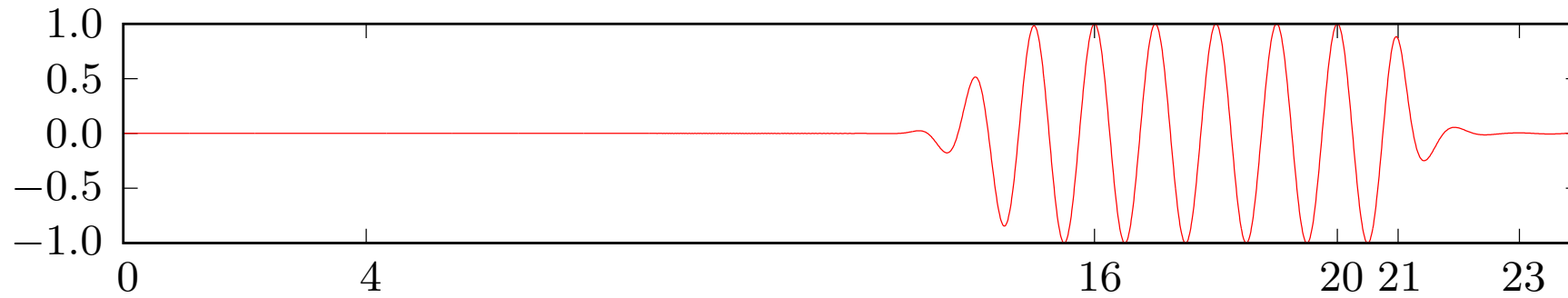
$$\begin{aligned}\frac{d}{dt} \int_0^L p dx &= - \int_0^L \mu p dx, & \frac{d}{dt} \int_0^L v dx &= - \int_0^L \nu v dx + p(0, t) - p(L, t), \\ \frac{d}{dt} \int_0^L \frac{1}{2} p^2 + \frac{1}{2} v^2 dx &= - \int_0^L \mu p^2 dx - \int_0^L \nu v^2 dx.\end{aligned}$$

Test case: 1D wave equation with damping

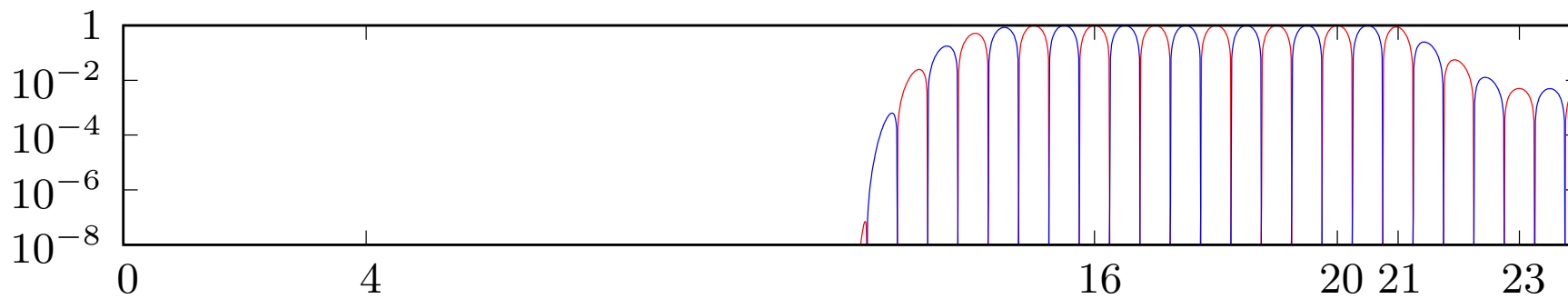
(a) $t = 0$



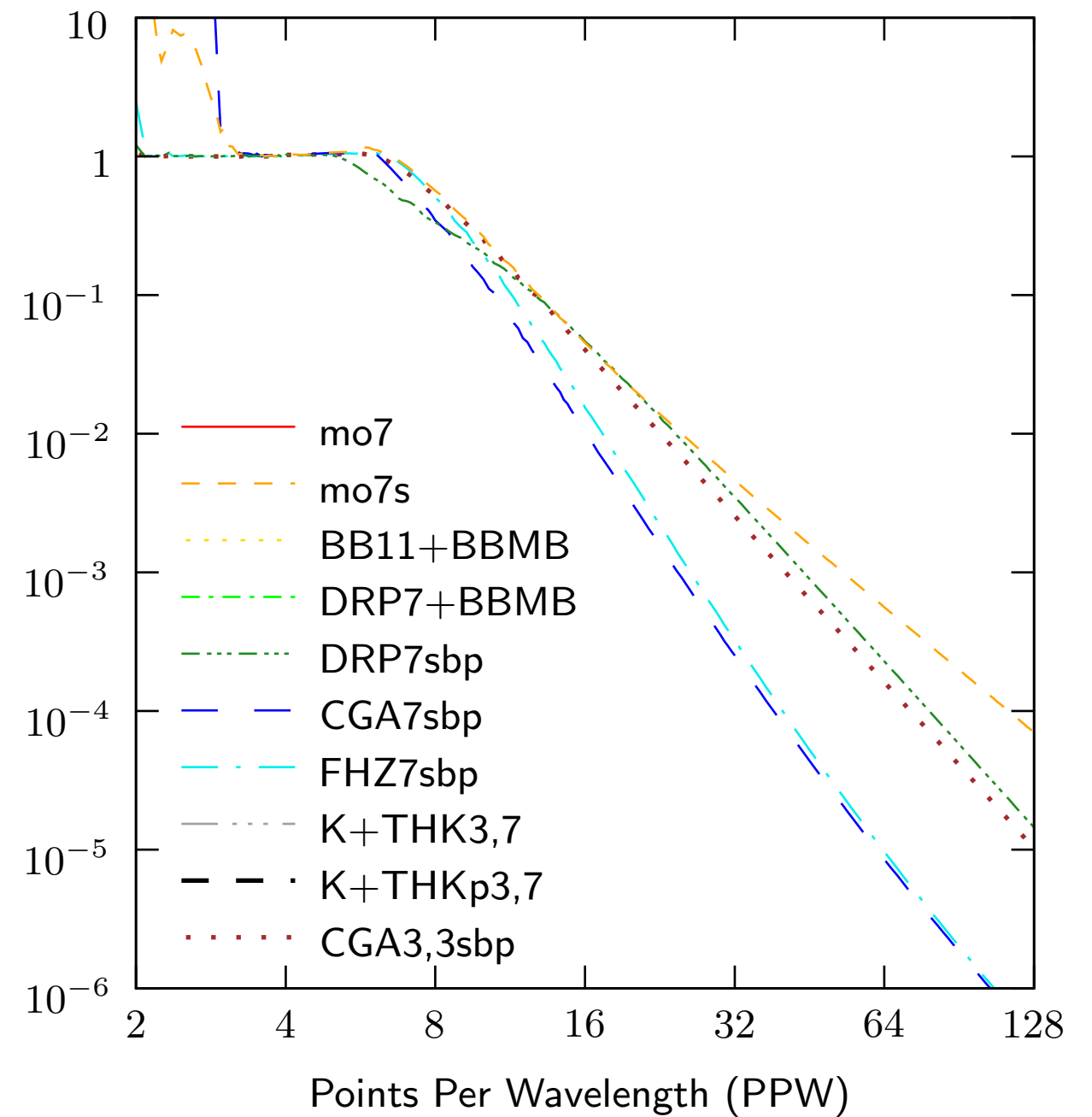
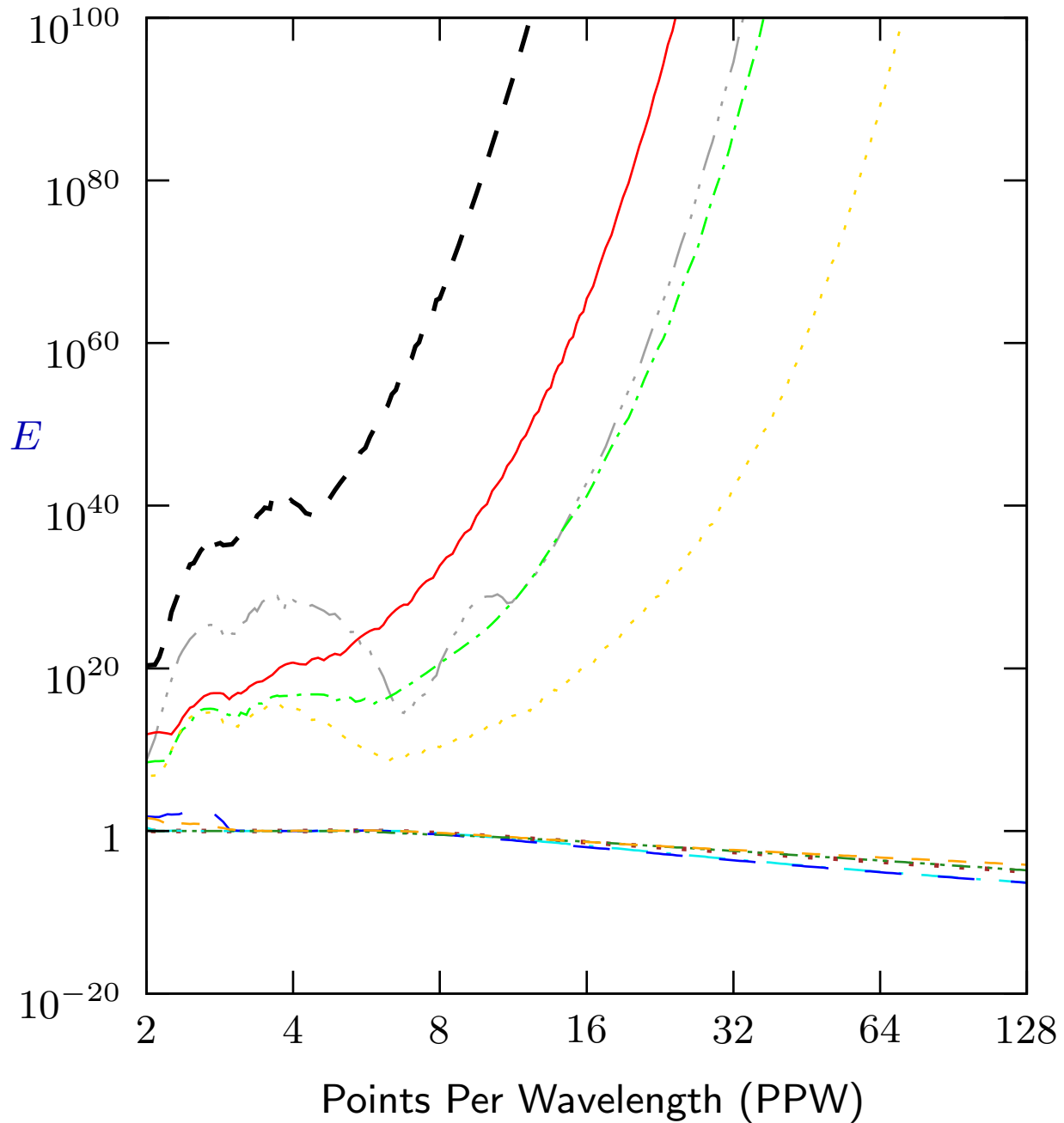
(b) $t = 12$



(c) $t = 12$ (logarithmic scale)



Test case performance



Summation by Parts (Strand, 1994)

- Integration by parts (IBP):

$$\langle f, g \rangle = \int_{x_0}^{x_N} f(x)g(x) dx \quad \Rightarrow \quad \left\langle f, \frac{dg}{dx} \right\rangle = f(x_N)g(x_N) - f(x_0)g(x_0) - \left\langle \frac{df}{dx}, g \right\rangle$$

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$$\langle f, g \rangle_{\mathbf{P}} = \mathbf{f}^T \mathbf{P} \mathbf{g} = \sum_{i,j=1}^N f_i P_{ij} g_j \quad \Rightarrow \quad \langle \mathbf{f}, D\mathbf{g} \rangle_{\mathbf{P}} = f_N g_N - f_0 g_0 - \langle D\mathbf{f}, \mathbf{g} \rangle_{\mathbf{P}}$$

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- Equivalently, $\mathbf{P}D = \mathbf{Q}$, with

$$\mathbf{P} = \mathbf{P}^T \quad \mathbf{Q} = -\mathbf{Q}^T + \mathbf{e}_N \mathbf{e}_N^T - \mathbf{e}_0 \mathbf{e}_0^T$$

Summation by Parts (4th order interior, 3rd order boundaries)

$$\Delta x \begin{pmatrix} \frac{173}{648} & \frac{41}{1296} & 0 & 0 \\ \frac{41}{1296} & \frac{1135}{648} & \frac{-353}{648} & \frac{17}{108} \\ 0 & \frac{-353}{648} & \frac{901}{648} & \frac{-151}{1296} \\ 0 & \frac{17}{108} & \frac{-151}{1296} & \frac{671}{648} \\ & & 1 & \\ & & & 1 \\ & & & \dots \end{pmatrix} \begin{pmatrix} f'_0 \\ f'_1 \\ f'_2 \\ f'_3 \\ f'_4 \\ f'_5 \\ \vdots \end{pmatrix} \\
 = \begin{pmatrix} \frac{-1}{2} & \frac{2035}{2592} & \frac{-239}{648} & \frac{217}{2592} \\ \frac{-2035}{2592} & 0 & \frac{829}{864} & \frac{-113}{648} \\ \frac{239}{648} & \frac{-829}{864} & 0 & \frac{1747}{2592} & \frac{-1}{12} \\ \frac{-217}{2592} & \frac{113}{648} & \frac{-1747}{2592} & 0 & \frac{2}{3} & \frac{-1}{12} \\ & & \frac{1}{12} & \frac{-2}{3} & 0 & \frac{2}{3} & \frac{-1}{12} \\ & & & \frac{1}{12} & \frac{-2}{3} & 0 & \frac{2}{3} & \frac{-1}{12} \\ & & & & \dots & \dots & \dots & \dots & \dots \end{pmatrix} \begin{pmatrix} f_0 \\ f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \\ \vdots \end{pmatrix}$$

Summation by Parts and stability

- Our problem is:

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$$\begin{aligned}\frac{d\mathbf{p}}{dt} + \mathbf{D}\mathbf{v} &= -\mathbf{M}\mathbf{p}, \\ \frac{d\mathbf{v}}{dt} + \mathbf{D}\mathbf{p} &= -\mathbf{N}\mathbf{v},\end{aligned}$$

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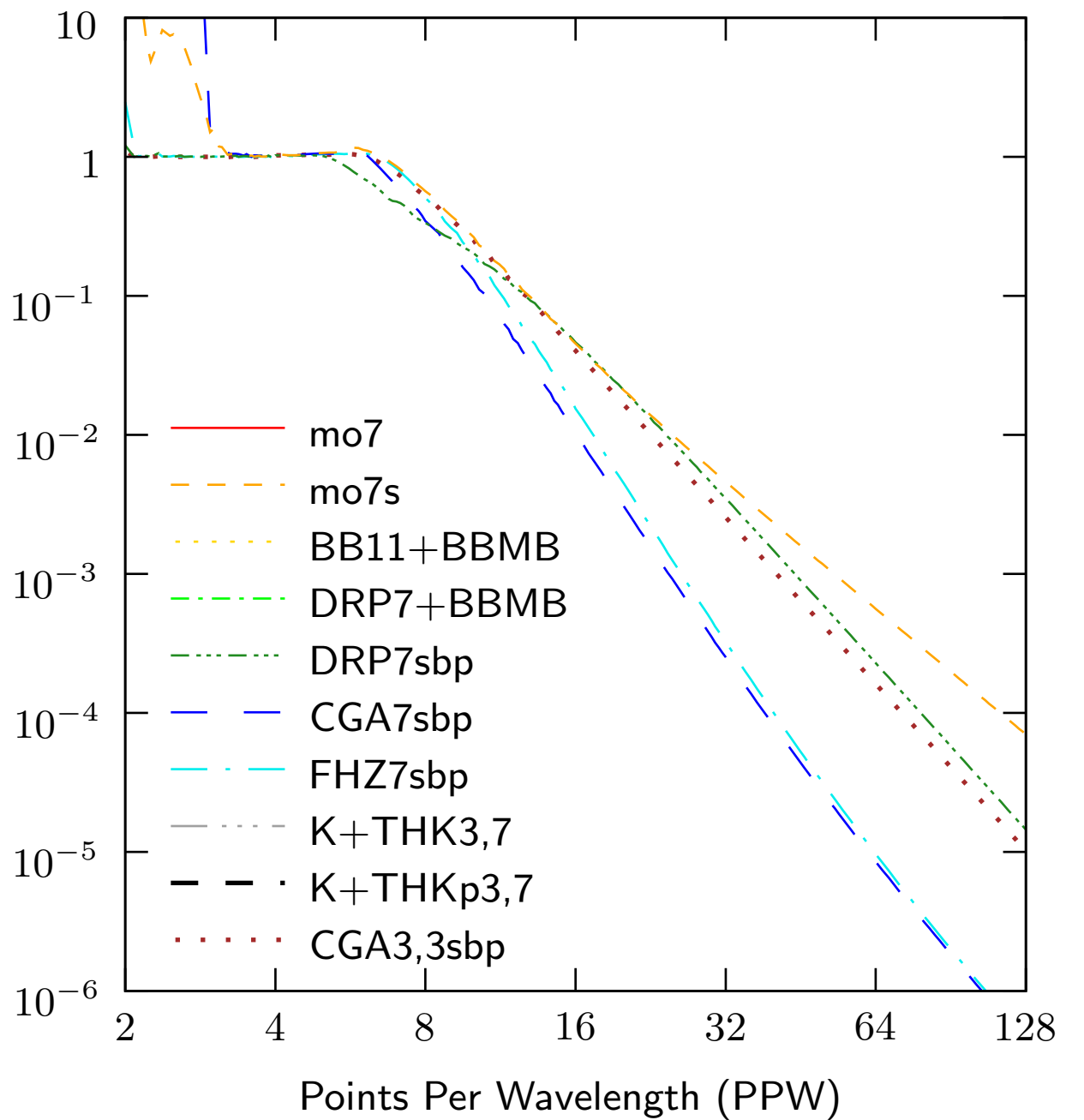
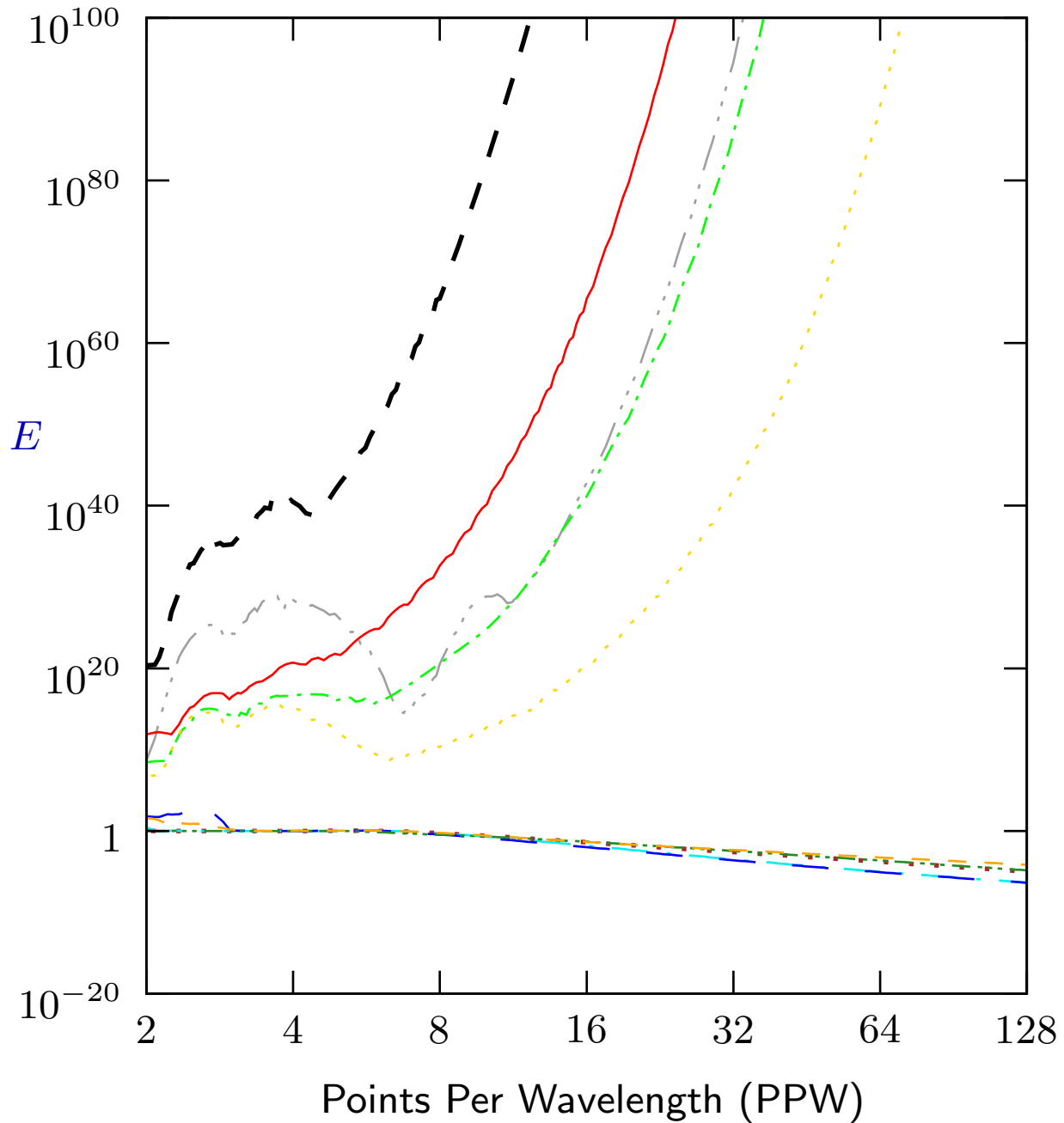
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- Discrete conservation law:

$$\begin{aligned}\frac{d}{dt} \left(\frac{1}{2} \langle \mathbf{p}, \mathbf{p} \rangle_P + \frac{1}{2} \langle \mathbf{v}, \mathbf{v} \rangle_P \right) &= \left\langle \mathbf{p}, \frac{d\mathbf{p}}{dt} \right\rangle_P + \left\langle \mathbf{v}, \frac{d\mathbf{v}}{dt} \right\rangle_P \\ &= - \left\langle \mathbf{p}, D\mathbf{v} + M\mathbf{p} \right\rangle_P - \left\langle \mathbf{v}, D\mathbf{p} + N\mathbf{v} \right\rangle_P \\ &= - \langle \mathbf{p}, D\mathbf{v} \rangle_P - \langle \mathbf{p}, M\mathbf{p} \rangle_P + \langle D\mathbf{v}, \mathbf{p} \rangle_P - \langle \mathbf{v}, N\mathbf{v} \rangle_P\end{aligned}$$

Test case performance



SBP Schemes from Interpolating Bases

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then \mathbf{P} and \mathbf{Q} have the SBP property:

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- Hence, all interpolating bases naturally lead to an SBP derivative scheme. But of what order?

SBP Schemes from Interpolating Bases: Order

- Finite differences are order $O(\Delta x^p)$ at position i if it is exact for all polynomials of degree p ,

$$\sum_j P_{ij} n x_j^{n-1} = \sum_j Q_{ij} x_j^n \quad \forall n = 0, 1, \dots, p.$$

- In interpolating basis notation,

$$\int_0^L \psi_i(x) \left(\sum_j n x_j^{n-1} \psi_j(x) - \sum_j x_j^n \psi_j'(x) \right) dx = 0 \quad \forall n = 0, 1, \dots, p.$$

SBP Schemes from Interpolating Bases: Order

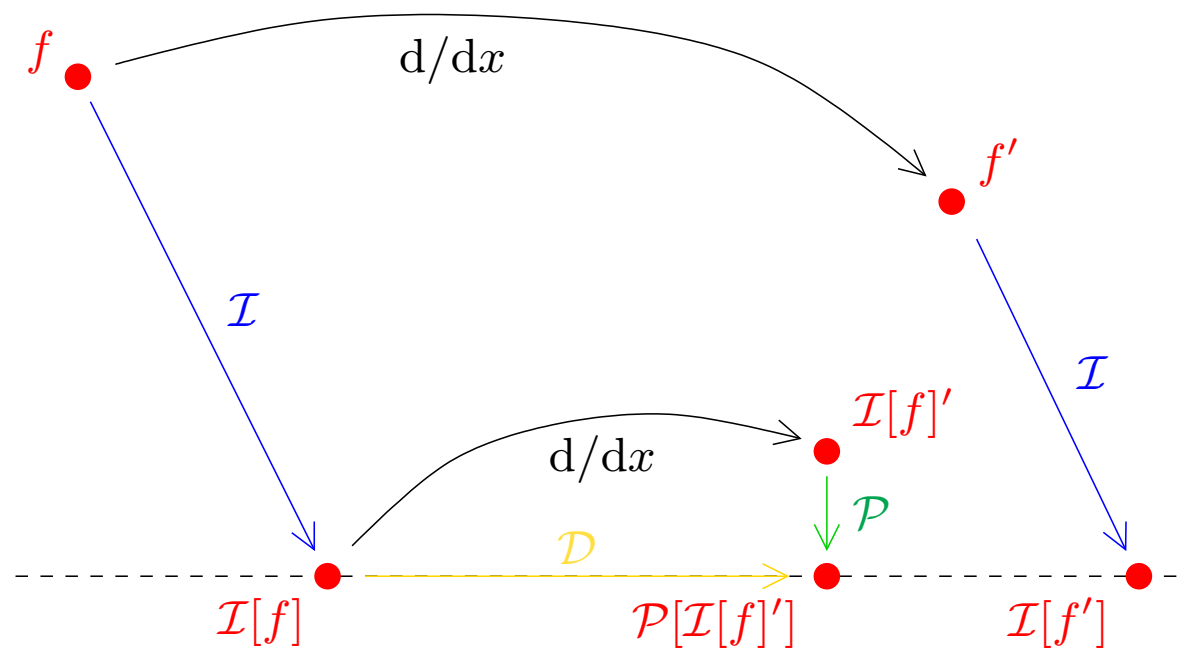
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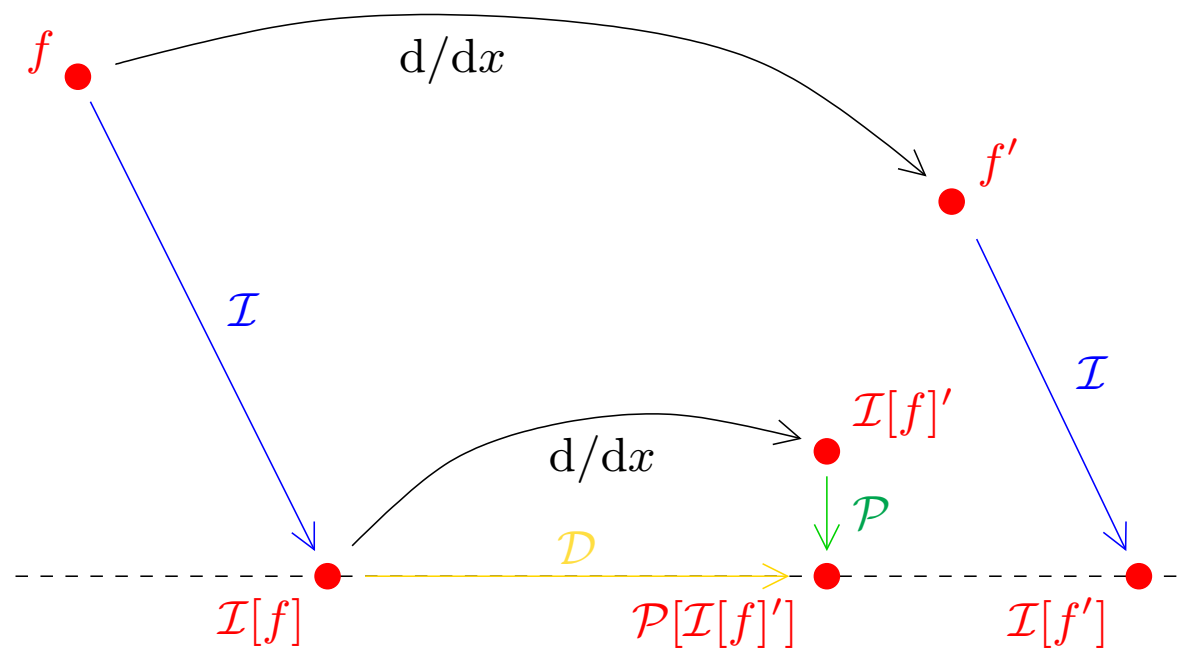
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- This is trivially true if $\mathcal{I}P = P$ for polynomials of degree p .

An example: Piecewise Linear Interpolation

- Take basis functions corresponding to piecewise linear interpolation,

$$\psi_j(x) = \begin{cases} 1 - |x - x_j| & |x - x_j| < 1 \\ 0 & |x - x_j| \geq 1 \end{cases}$$

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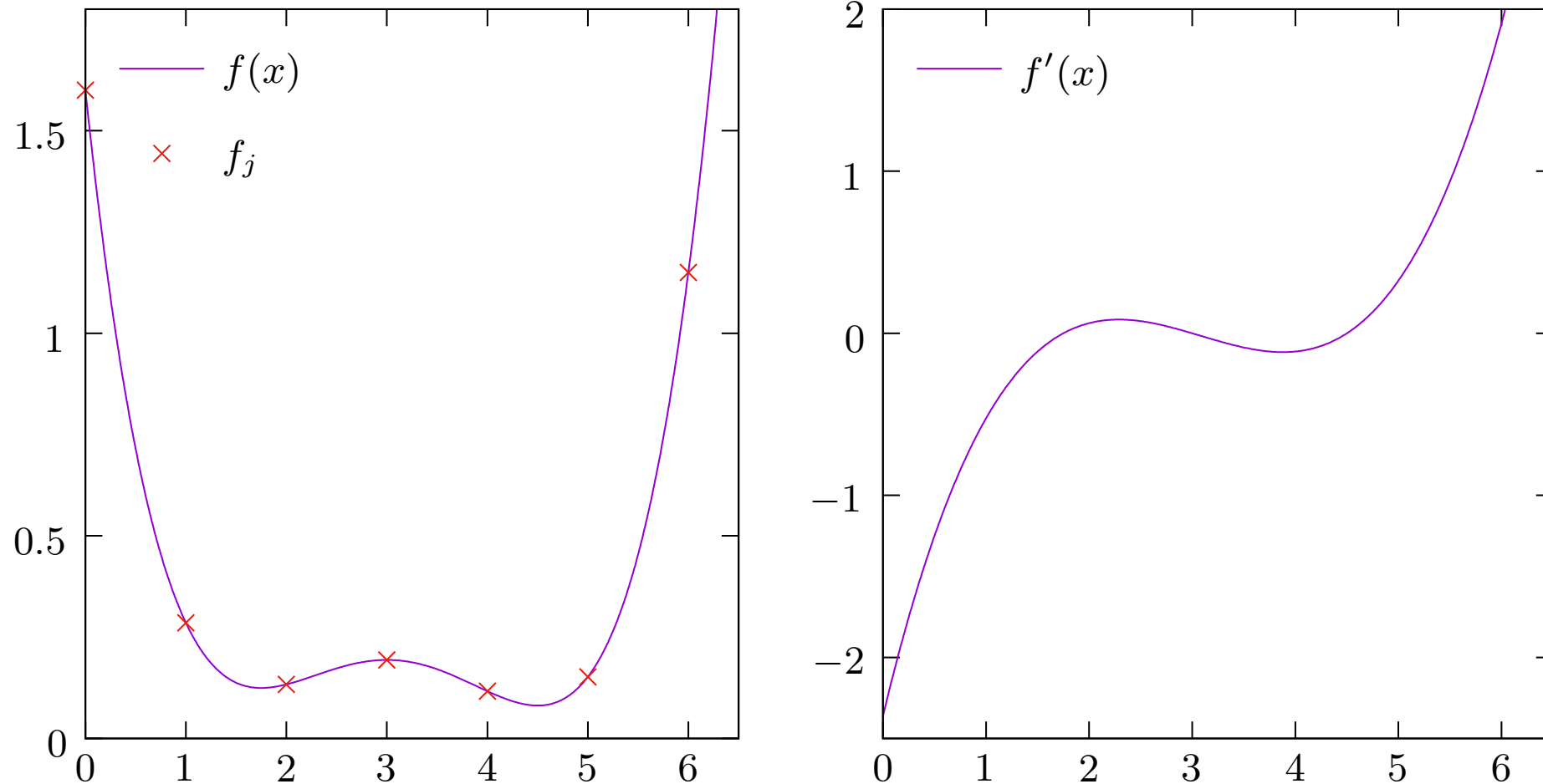
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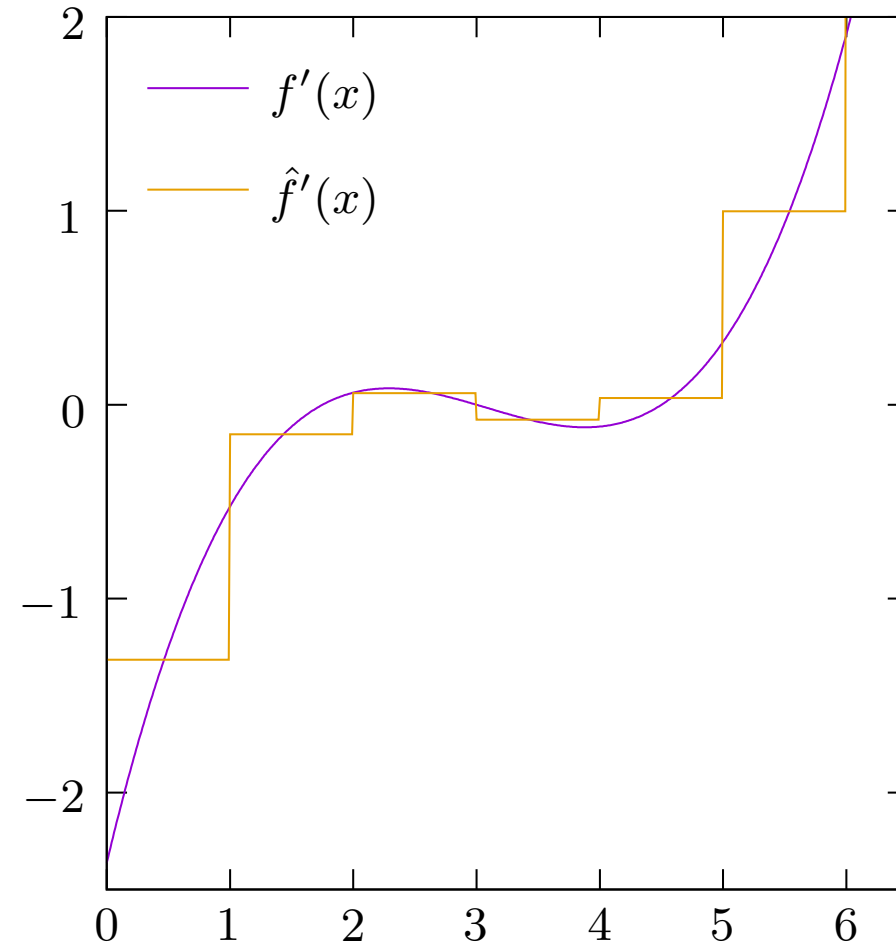
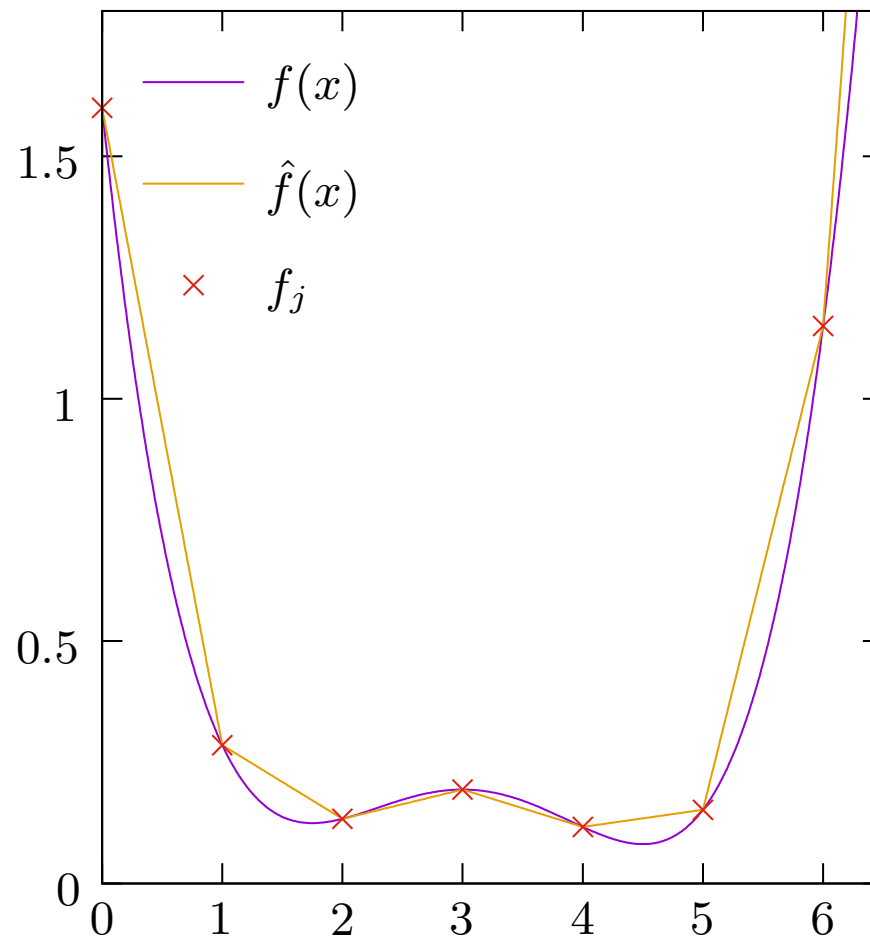


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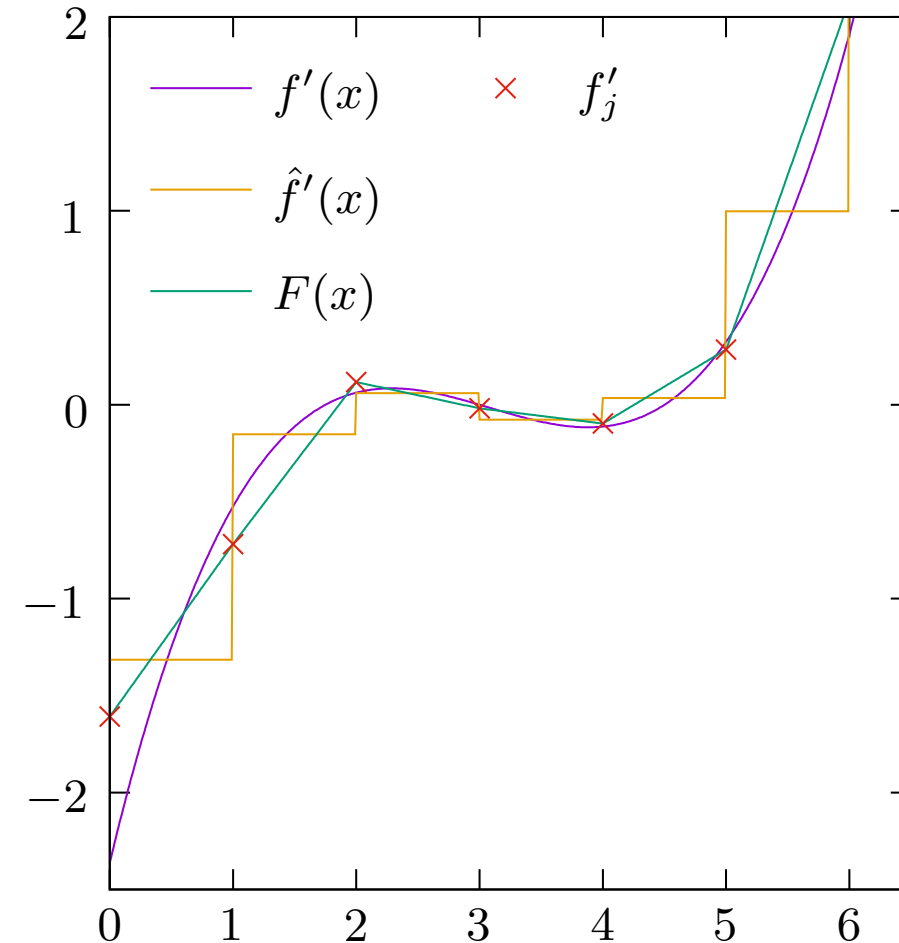
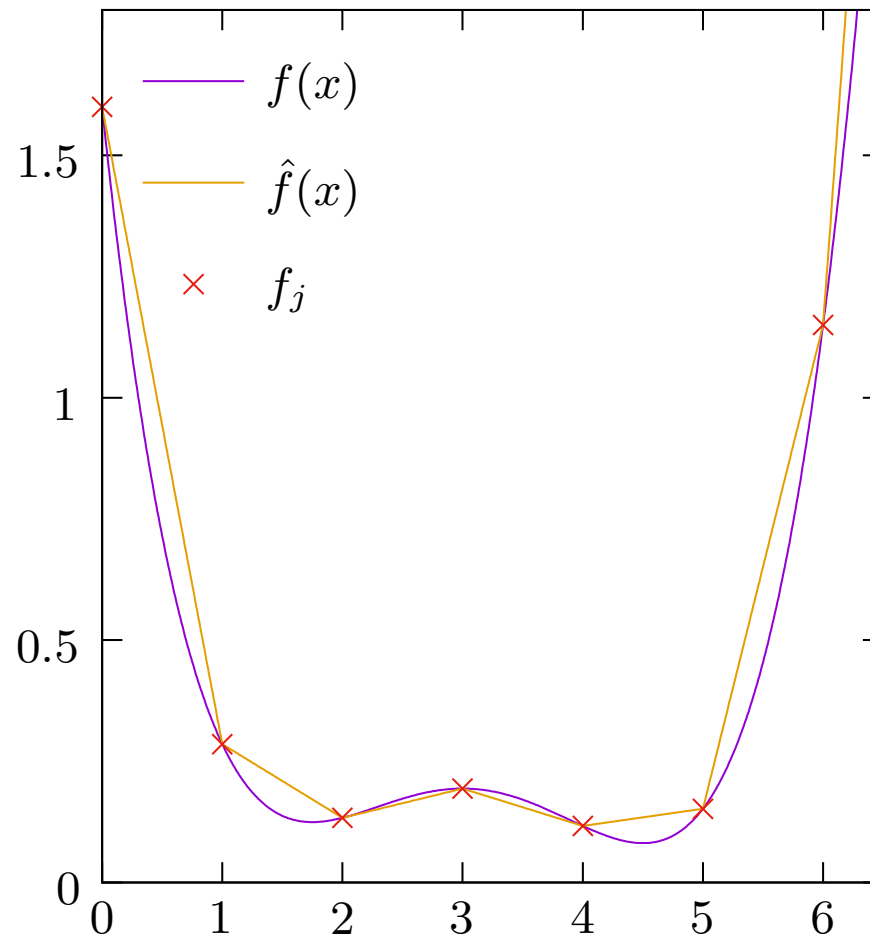


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- By calculation, we find

$$P_{ij} = \int_0^L \psi_i(x)\psi_j(x) dx = \begin{pmatrix} \frac{1}{3} & \frac{1}{6} & & & \\ \frac{1}{6} & \frac{2}{3} & \frac{1}{6} & & \\ & \frac{1}{6} & \frac{2}{3} & \frac{1}{6} & \\ & & \ddots & \ddots & \ddots \end{pmatrix}, \quad Q_{ij} = \int_0^L \psi_i(x)\psi_j'(x) dx = \begin{pmatrix} -\frac{1}{2} & \frac{1}{2} & & & \\ -\frac{1}{2} & 0 & \frac{1}{2} & & \\ & -\frac{1}{2} & 0 & \frac{1}{2} & \\ & & \ddots & \ddots & \ddots \end{pmatrix}.$$

- ◆ This is a 4th order tri-diagonal maximal order scheme in the interior.
- ◆ It is only 1st order at the boundary.
- ◆ The interpolation is only exact for polynomials of degree 1.